**LAB CYCLE 5**

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**ROLL NO : MCA107**

**S1 MCA**

**1.PRIM’S ALGORITHM**

#include<stdio.h>

#include<stdlib.h>

#define infinity 9999

#define MAX 20

int G[MAX][MAX],spanning[MAX][MAX],n;

int prims();

int main()

{

int i,j,total\_cost;

printf("Enter no. of vertices:");

scanf("%d",&n);

printf("\nEnter the adjacency matrix:\n");

for(i=0;i<n;i++)

for(j=0;j<n;j++)

scanf("%d",&G[i][j]);

total\_cost=prims();

printf("\nspanning tree matrix:\n");

for(i=0;i<n;i++)

{

printf("\n");

for(j=0;j<n;j++)

printf("%d\t",spanning[i][j]);

}

printf("\n\nTotal cost of spanning tree=%d",total\_cost);

return 0;

}

int prims()

{

int cost[MAX][MAX];

int u,v,min\_distance,distance[MAX],from[MAX];

int visited[MAX],no\_of\_edges,i,min\_cost,j;

//create cost[][] matrix,spanning[][]

for(i=0;i<n;i++)

for(j=0;j<n;j++)

{

if(G[i][j]==0)

cost[i][j]=infinity;

else

cost[i][j]=G[i][j];

spanning[i][j]=0;

}

//initialise visited[],distance[] and from[]

distance[0]=0;

visited[0]=1;

for(i=1;i<n;i++)

{

distance[i]=cost[0][i];

from[i]=0;

visited[i]=0;

}

min\_cost=0; //cost of spanning tree

no\_of\_edges=n-1; //no. of edges to be added

while(no\_of\_edges>0)

{

//find the vertex at minimum distance from the tree

min\_distance=infinity;

for(i=1;i<n;i++)

if(visited[i]==0&&distance[i]<min\_distance)

{

v=i;

min\_distance=distance[i];

}

u=from[v];

spanning[u][v]=distance[v];

spanning[v][u]=distance[v];

no\_of\_edges--;

visited[v]=1;

for(i=1;i<n;i++)

if(visited[i]==0&&cost[i][v]<distance[i])

{

distance[i]=cost[i][v];

from[i]=v;

}

min\_cost=min\_cost+cost[u][v];

}

return(min\_cost);

}

**2.KRUSKAL’S ALGORITHM**

#include<stdio.h>

#define MAX 30

typedef struct edge

{

int u,v,w;

}edge;

typedef struct edgelist

{

edge data[MAX];

int n;

}edgelist;

edgelist elist;

int G[MAX][MAX],n;

edgelist spanlist;

void kruskal();

int find(int belongs[],int vertexno);

void union1(int belongs[],int c1,int c2);

void sort();

void print();

void main()

{

int i,j,total\_cost;

printf("\nEnter number of vertices:");

scanf("%d",&n);

printf("\nEnter the adjacency matrix:\n");

for(i=0;i<n;i++)

for(j=0;j<n;j++)

scanf("%d",&G[i][j]);

kruskal();

print();

}

void kruskal()

{

int belongs[MAX],i,j,cno1,cno2;

elist.n=0;

for(i=1;i<n;i++)

for(j=0;j<i;j++)

{

if(G[i][j]!=0)

{

elist.data[elist.n].u=i;

elist.data[elist.n].v=j;

elist.data[elist.n].w=G[i][j];

elist.n++;

}

}

sort();

for(i=0;i<n;i++)

belongs[i]=i;

spanlist.n=0;

for(i=0;i<elist.n;i++)

{

cno1=find(belongs,elist.data[i].u);

cno2=find(belongs,elist.data[i].v);

if(cno1!=cno2)

{

spanlist.data[spanlist.n]=elist.data[i];

spanlist.n=spanlist.n+1;

union1(belongs,cno1,cno2);

}

}

}

int find(int belongs[],int vertexno)

{

return(belongs[vertexno]);

}

void union1(int belongs[],int c1,int c2)

{

int i;

for(i=0;i<n;i++)

if(belongs[i]==c2)

belongs[i]=c1;

}

void sort()

{

int i,j;

edge temp;

for(i=1;i<elist.n;i++)

for(j=0;j<elist.n-1;j++)

if(elist.data[j].w>elist.data[j+1].w)

{

temp=elist.data[j];

elist.data[j]=elist.data[j+1];

elist.data[j+1]=temp;

}

}

void print()

{

int i,cost=0;

for(i=0;i<spanlist.n;i++)

{

printf("\n%d\t%d\t%d",spanlist.data[i].u,spanlist.data[i].v,spanlist.data[i].w);

cost=cost+spanlist.data[i].w;

}

printf("\n\nCost of the spanning tree=%d",cost);

}

**3.SINGLE SOURCE SHORTEST PATH ALGORITHM**

#include <stdio.h>

#define INFINITY 9999

#define MAX 10

void Dijkstra(int Graph[MAX][MAX], int n, int start);

void Dijkstra(int Graph[MAX][MAX], int n, int start) {

int cost[MAX][MAX], distance[MAX], pred[MAX];

int visited[MAX], count, mindistance, nextnode, i, j;

// Creating cost matrix

for (i = 0; i < n; i++)

for (j = 0; j < n; j++)

if (Graph[i][j] == 0)

cost[i][j] = INFINITY;

else

cost[i][j] = Graph[i][j];

for (i = 0; i < n; i++) {

distance[i] = cost[start][i];

pred[i] = start;

visited[i] = 0;

}

distance[start] = 0;

visited[start] = 1;

count = 1;

while (count < n - 1) {

mindistance = INFINITY;

for (i = 0; i < n; i++)

if (distance[i] < mindistance && !visited[i]) {

mindistance = distance[i];

nextnode = i;

}

visited[nextnode] = 1;

for (i = 0; i < n; i++)

if (!visited[i])

if (mindistance + cost[nextnode][i] < distance[i]) {

distance[i] = mindistance + cost[nextnode][i];

pred[i] = nextnode;

}

count++;

}

// Printing the distance

for (i = 0; i < n; i++)

if (i != start) {

printf("\nDistance from source to %d: %d", i, distance[i]);

}

}

int main() {

int Graph[MAX][MAX], i, j, n, u;

n = 7;

Graph[0][0] = 0;

Graph[0][1] = 0;

Graph[0][2] = 1;

Graph[0][3] = 2;

Graph[0][4] = 0;

Graph[0][5] = 0;

Graph[0][6] = 0;

Graph[1][0] = 0;

Graph[1][1] = 0;

Graph[1][2] = 2;

Graph[1][3] = 0;

Graph[1][4] = 0;

Graph[1][5] = 3;

Graph[1][6] = 0;

Graph[2][0] = 1;

Graph[2][1] = 2;

Graph[2][2] = 0;

Graph[2][3] = 1;

Graph[2][4] = 3;

Graph[2][5] = 0;

Graph[2][6] = 0;

Graph[3][0] = 2;

Graph[3][1] = 0;

Graph[3][2] = 1;

Graph[3][3] = 0;

Graph[3][4] = 0;

Graph[3][5] = 0;

Graph[3][6] = 1;

Graph[4][0] = 0;

Graph[4][1] = 0;

Graph[4][2] = 3;

Graph[4][3] = 0;

Graph[4][4] = 0;

Graph[4][5] = 2;

Graph[4][6] = 0;

Graph[5][0] = 0;

Graph[5][1] = 3;

Graph[5][2] = 0;

Graph[5][3] = 0;

Graph[5][4] = 2;

Graph[5][5] = 0;

Graph[5][6] = 1;

Graph[6][0] = 0;

Graph[6][1] = 0;

Graph[6][2] = 0;

Graph[6][3] = 1;

Graph[6][4] = 0;

Graph[6][5] = 1;

Graph[6][6] = 0;

u = 0;

Dijkstra(Graph, n, u);

printf("\n");

return 0;

}

**LINK TO GITHUB REPOSITORY:**

[**https://github.com/NandanaAnil/Data-Structures.git**](https://github.com/NandanaAnil/Data-Structures.git)